

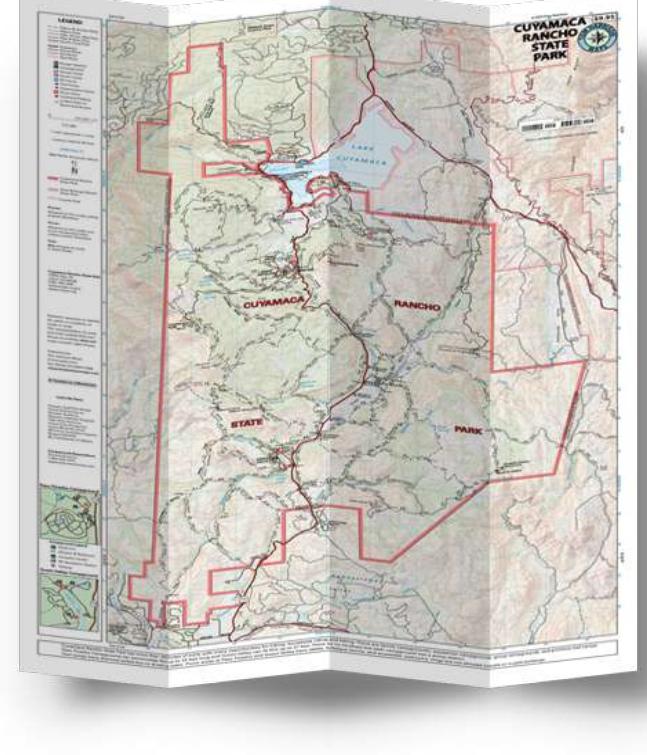
# Wave : A Substrate for Distributed Incremental Graph Processing on Commodity Cluster

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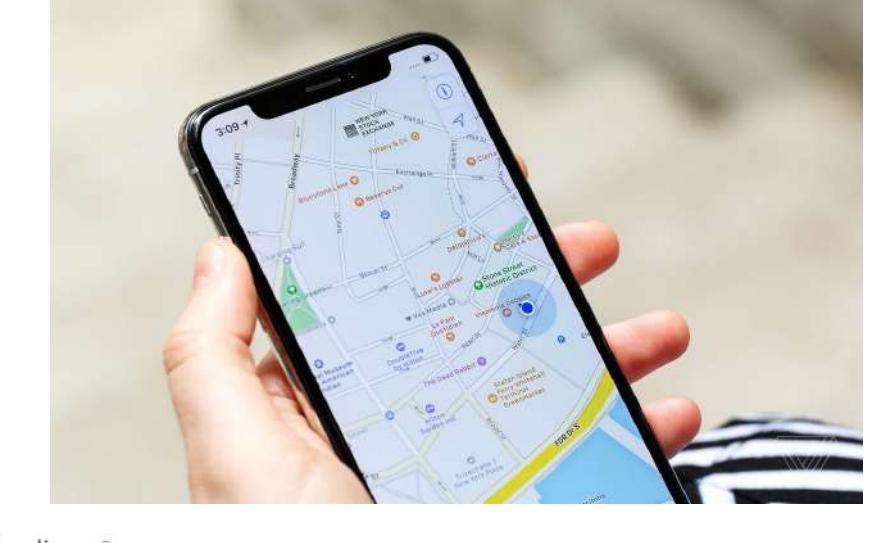
## INTRODUCTION

- Graphs are widely considered to be natural means of representation for many networks.
- Real-world networks are often evolving with links being added or removed and properties updated over time.

Examples : Social, Citation/Collaboration, Sensor, Financial & Transit Network, Human Connectomes, Internet-of-Things ...



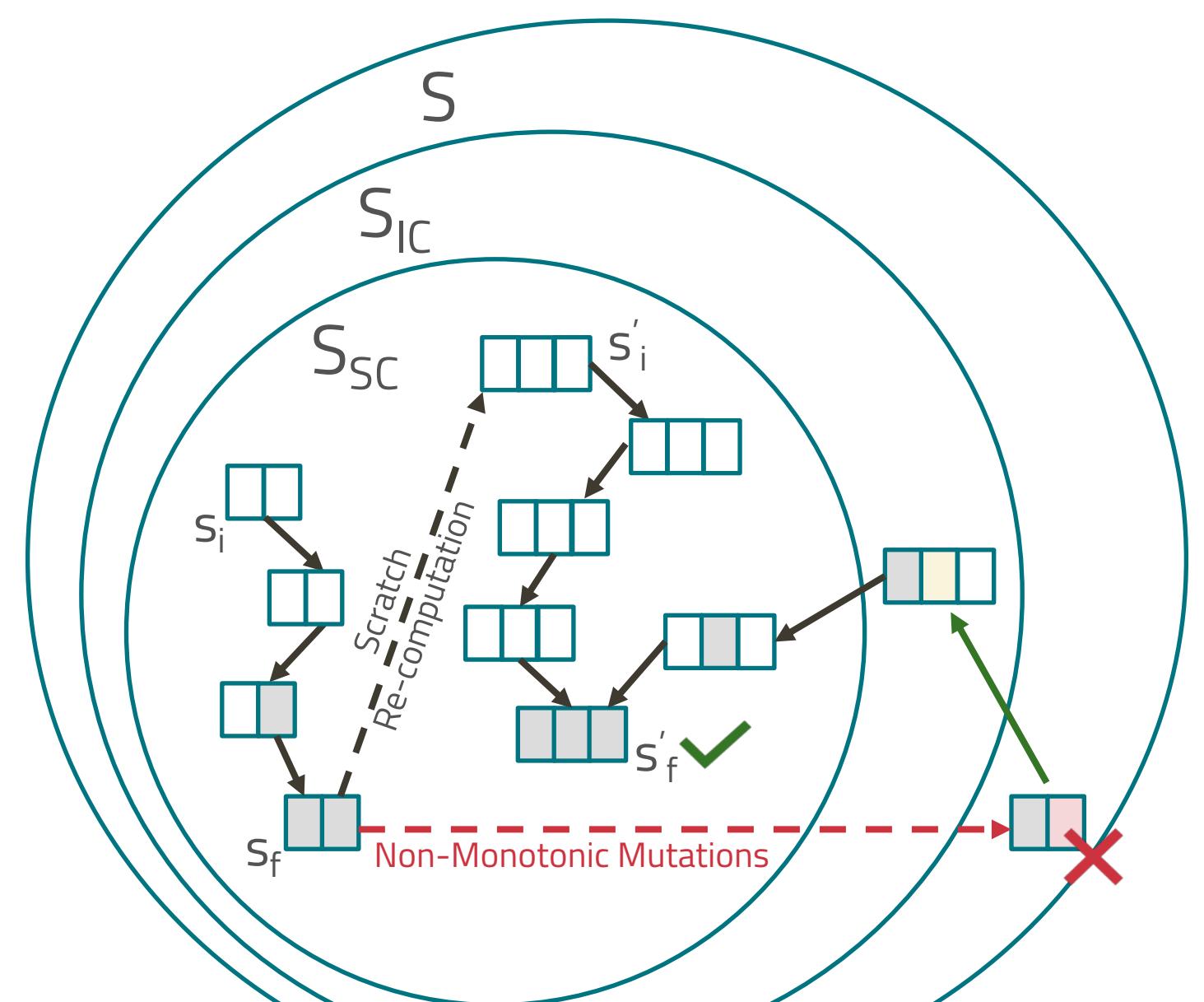
(a) Paper Map



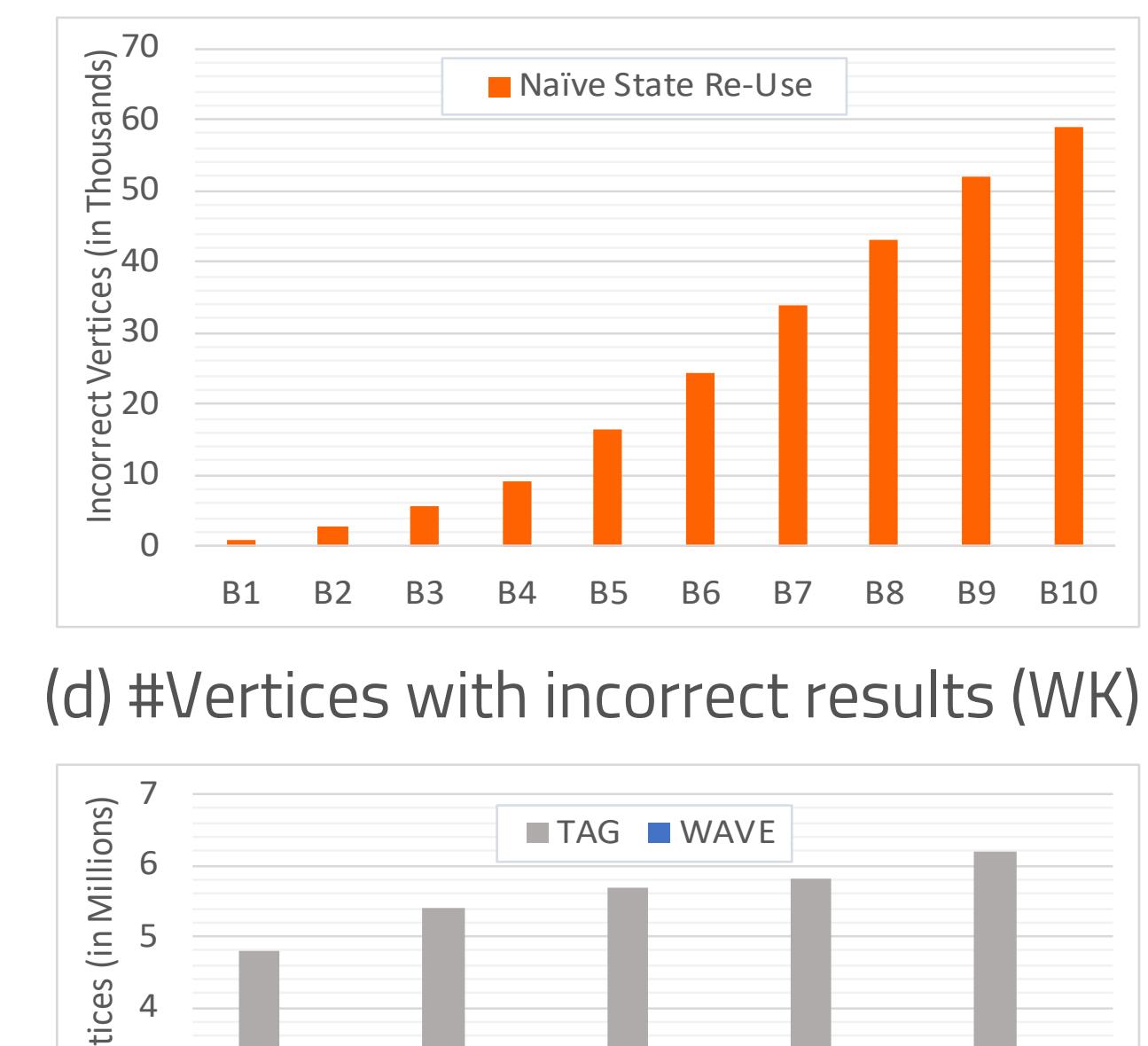
(b) Google Maps

- Incremental computation is used to process such dynamic graphs.

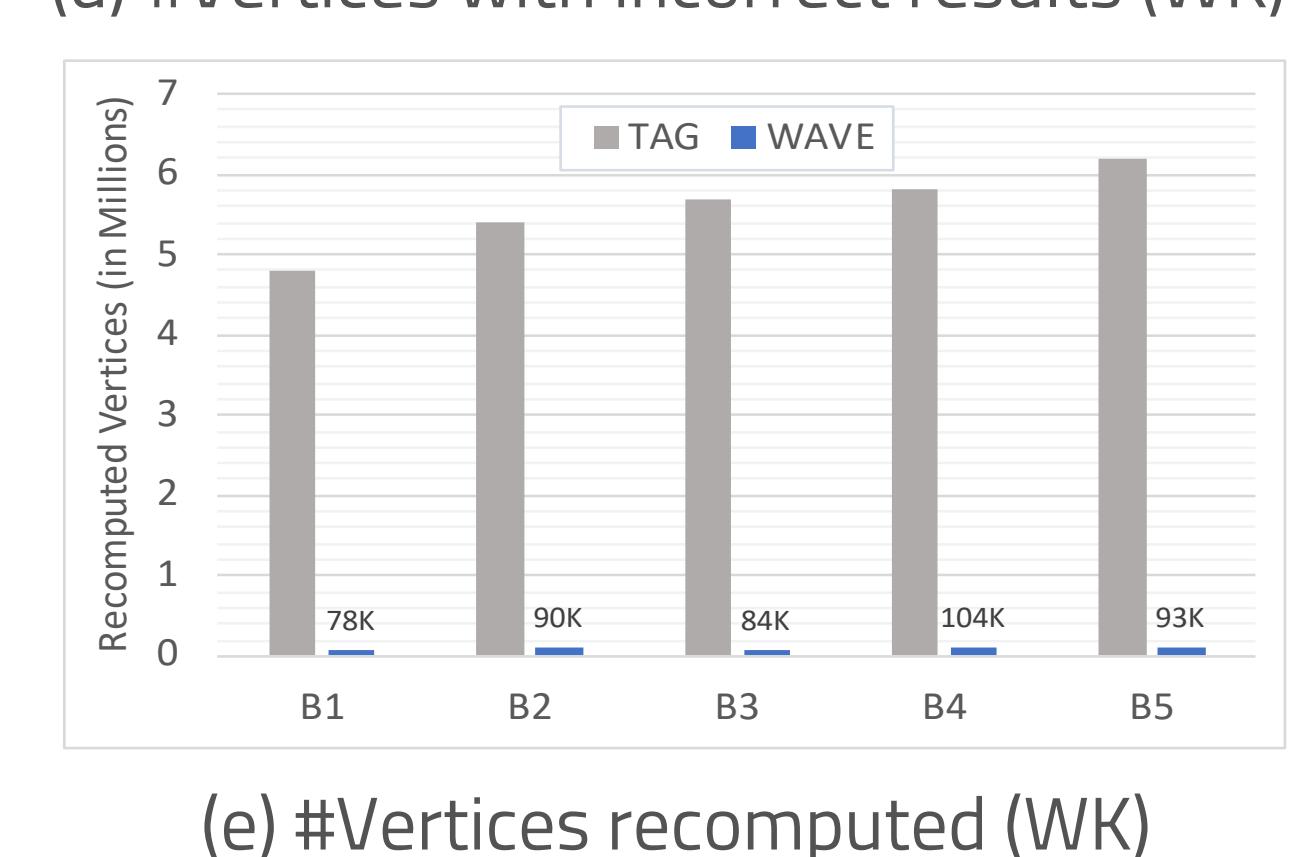
It achieves efficiency by minimizing redundant computation and communication compared to complete, from-scratch computation.



(c) Incremental processing of dynamic graphs



(d) #Vertices with incorrect results (WK)



(e) #Vertices recomputed (WK)

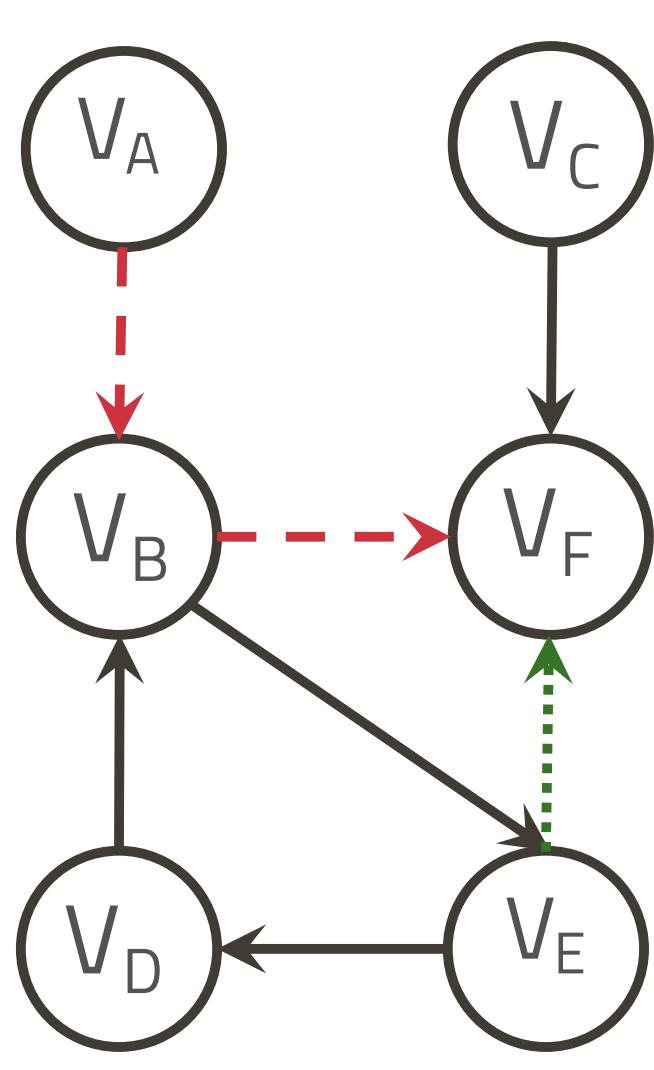
## Challenges:

- Safety: Reusing intermediate state naively leads to incorrect results.
- Profitability: Conservative tag-propagation guarantees safety, however limits state reuse ↪ ends up resetting majority of vertices.
- Lack of unifying abstraction to operate on dynamic graphs.

Existing abstractions either work for a sub-class of algorithms or lack support for non-monotonic updates. Specialized algorithms are designed for single-threaded shared-memory execution.

**This Work :** General-purpose distributed programming model to support incremental processing over dynamic graphs while leveraging existing vertex-centric semantics.

## CONNECTED COMPONENTS



(f) Dynamic graph

Before Deletes	V <sub>A</sub>	V <sub>B</sub>	V <sub>C</sub>	V <sub>D</sub>	V <sub>E</sub>	V <sub>F</sub>
	A	A	C	A	A	A
$V_A \rightarrow V_B$ and $V_B \rightarrow V_F$ Deleted						
	A	<b>B</b>	C	A	A	<b>F</b>
	A	B	C	A	<b>B</b>	F
After Deletes						
	A	B	C	<b>B</b>	B	<b>C</b>
$V_E \rightarrow V_F$ Inserted						
	A	B	C	B	B	B
After Insert						

(g) Vertex state updates over supersteps when finding Connected Components. Changes shown in red.

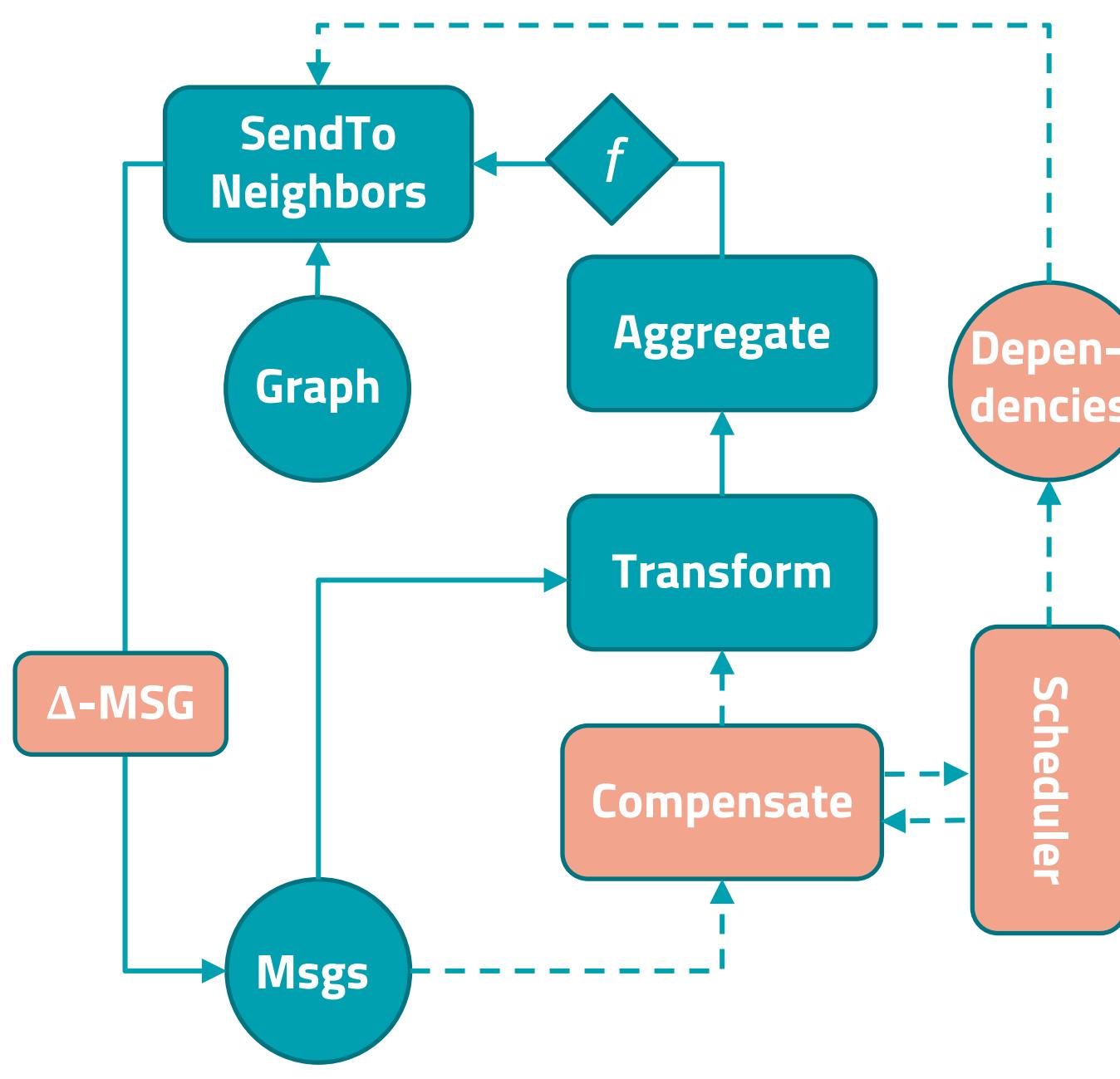
1  
2  
3  
4  
5  
6  
Supersteps

## SUMMARY

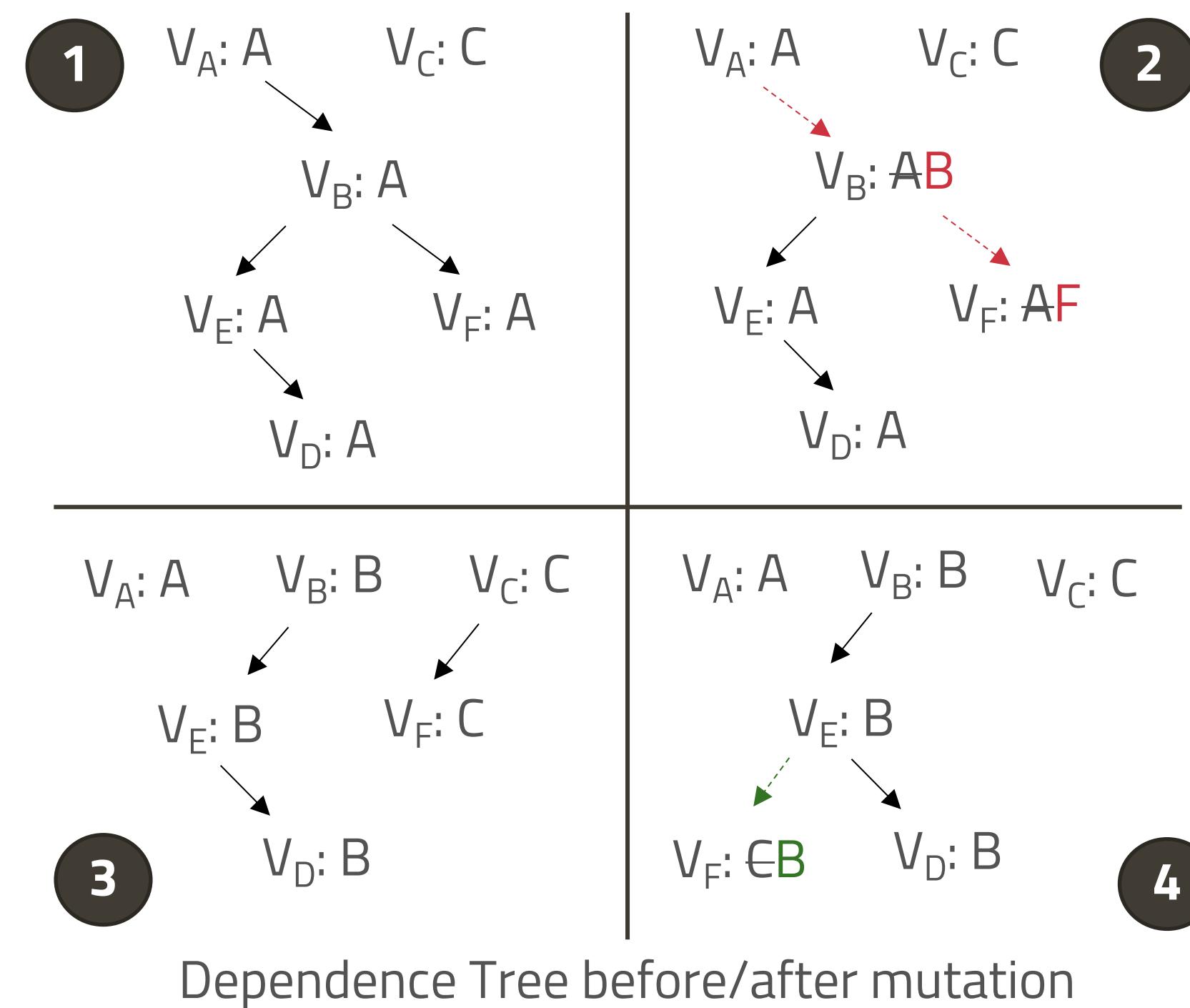
Incremental Graph Processing ↪ Better state re-use ↪ Minimized redundant computation and communication ↪ Faster convergence time

## INCREMENTAL GRAPH COMPUTATION

- Transparency:** We do not require the vertex program to be made incremental, but instead **incrementalize its boundary**.
  - Makes the approach applicable to all existing vertex programs
  - Requires minimal additional effort from the programmer to devise an incremental algorithm
- Framework identifies vertices directly and transitively affected by graph mutations.
  - Only parts of the graph **affected** by input changes are re-computed
  - Graph structure used to **actively deduce** value dependencies



Incremental Vertex Program in Wave



Dependence Tree before/after mutation

```

1 void compensate(vertex v, Message[] msgs,
2     boolean reScheduledCompute) {
3     Message[] cMsgs;
4     for(Message msg : msgs) {
5         if(msg.getType() ==
6             MessageType.RETRACT) {
7             retract(vertex v, msg);
8         } else {
9             cMsgs.append(msg);
10        } v.dequeueDeferredMsg(msg.getSRC());
11    }
12    for(Message deferredMsg :
13        v.getDeferredMsgs()) {
14        if(deferredMsg.getCurrentSuperstepTillDeferred()
15            == getCurrentSuperstep()) {
16            cMsgs.append(deferredMsg);
17            v.dequeueDeferredMsg(deferredMsg);
18        }
19    }
20    if(isVertexStateAffected()) {
21        deferMsgs(v, cMsgs);
22        if(isInvertible() || reScheduledCompute){
23            compute(v, cMsgs);
24        } else {
25            gatherStateFromInNeighbors(v);
26            rescheduleCompute();
27        }
28    }
29}

```

Master Program

```

1 void init(vertex v) {
2     v.setState(v.getId());
3     v.sendToAllNeighbors(v.getState());
4 }
5
6 void compute(vertex v, Message[] msgs) {
7     minCC = ∞;
8     for(Message msg : msgs) {
9         minCC = min(msg, minCC);
10    if(minCC < v.getState()) {
11        v.setState(minCC);
12        v.sendToAllNeighbors(v.getState());
13    }
14 }
15
16 void retract() {
17     if(v.getState().getSRC()==msg.getSRC()) {
18         init();
19    }
20
21 Message repropagate(vertex v, int dst) {
22     return new Message(v.getState());
23 }

```

User Program

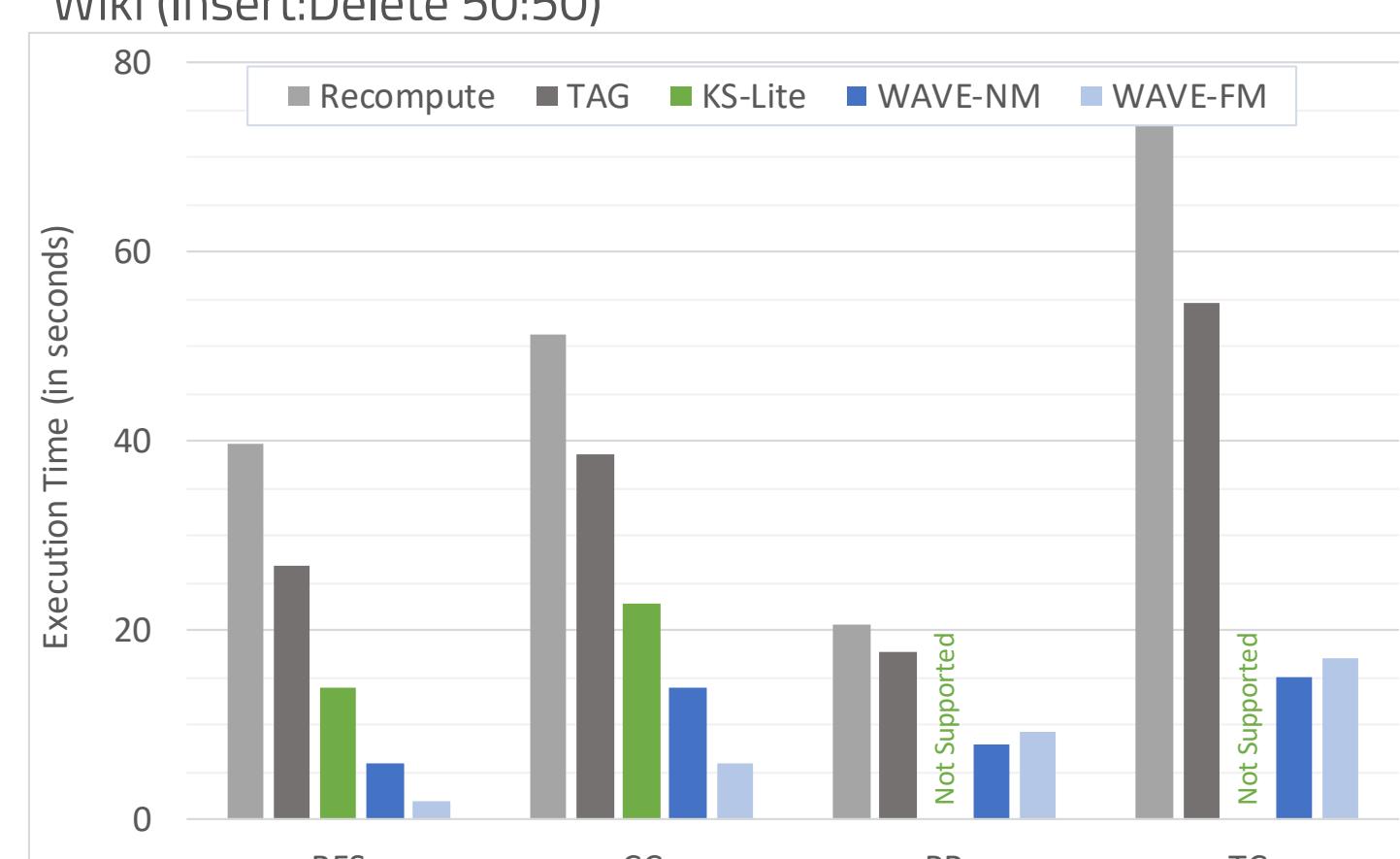
## EXPERIMENTAL EVALUATION

Algorithm	Aggregation
BFS	$\min_{v \in \{u,v\} \in E} (s(u) + 1)$
CC	$\min(v_i, \min_{v \in \{u,v\} \in E} u)$
PR	$\sum_{v \in \{u,v\} \in E} \frac{s(u)}{\text{out\_degree}(u)}$
TC	$\sum_{v \in \{u,v\} \in E}  \text{in\_neighbors}(u) \cap \text{out\_neighbors}(v) $

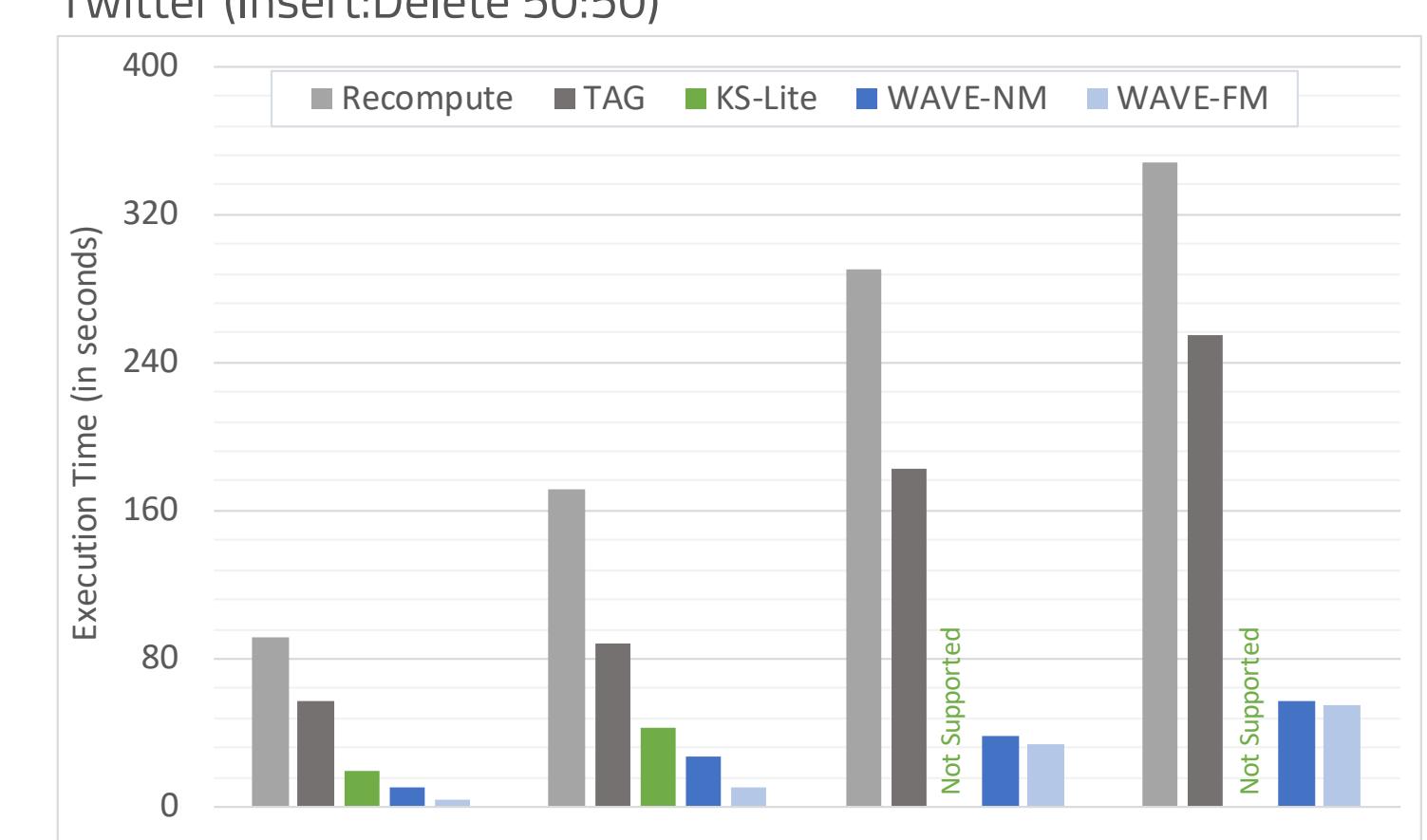
Graph	Vertices	Edges
Wiki (WK)	12M	378M
Twitter (TW)	41M	1.4B

8 Servers (Gigabit Ethernet)  
Server : 16 threads / 2.1 GHz / 64 GBs  
Apache Giraph 1.3 / Java 8.0

### Wiki (Insert:Delete 50:50)

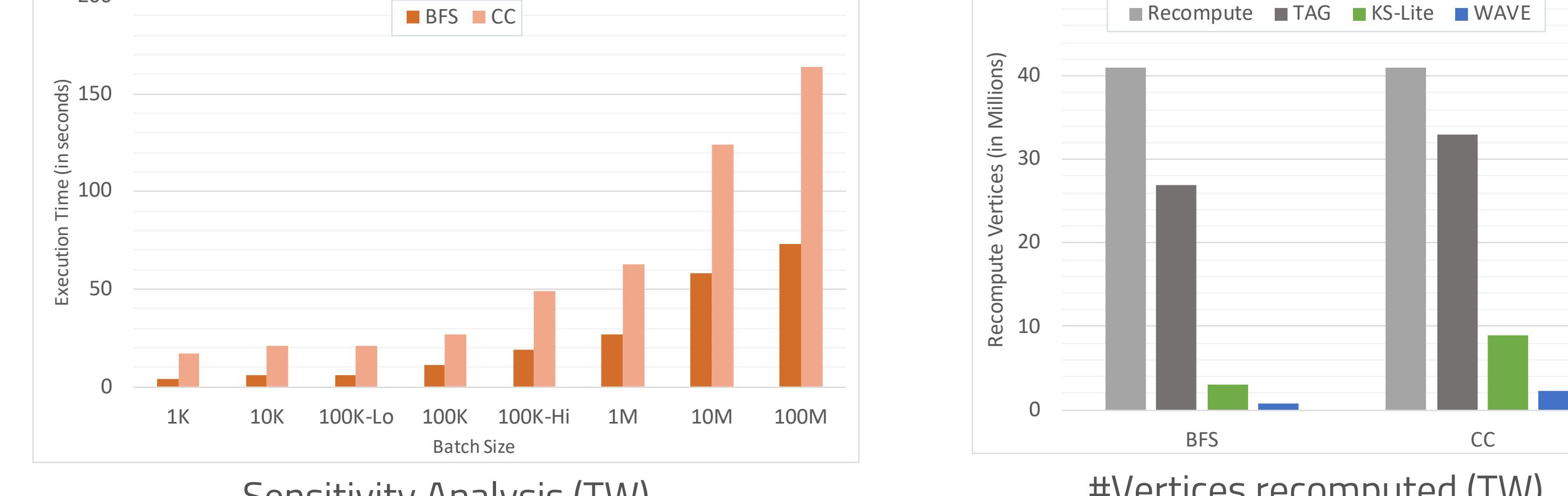
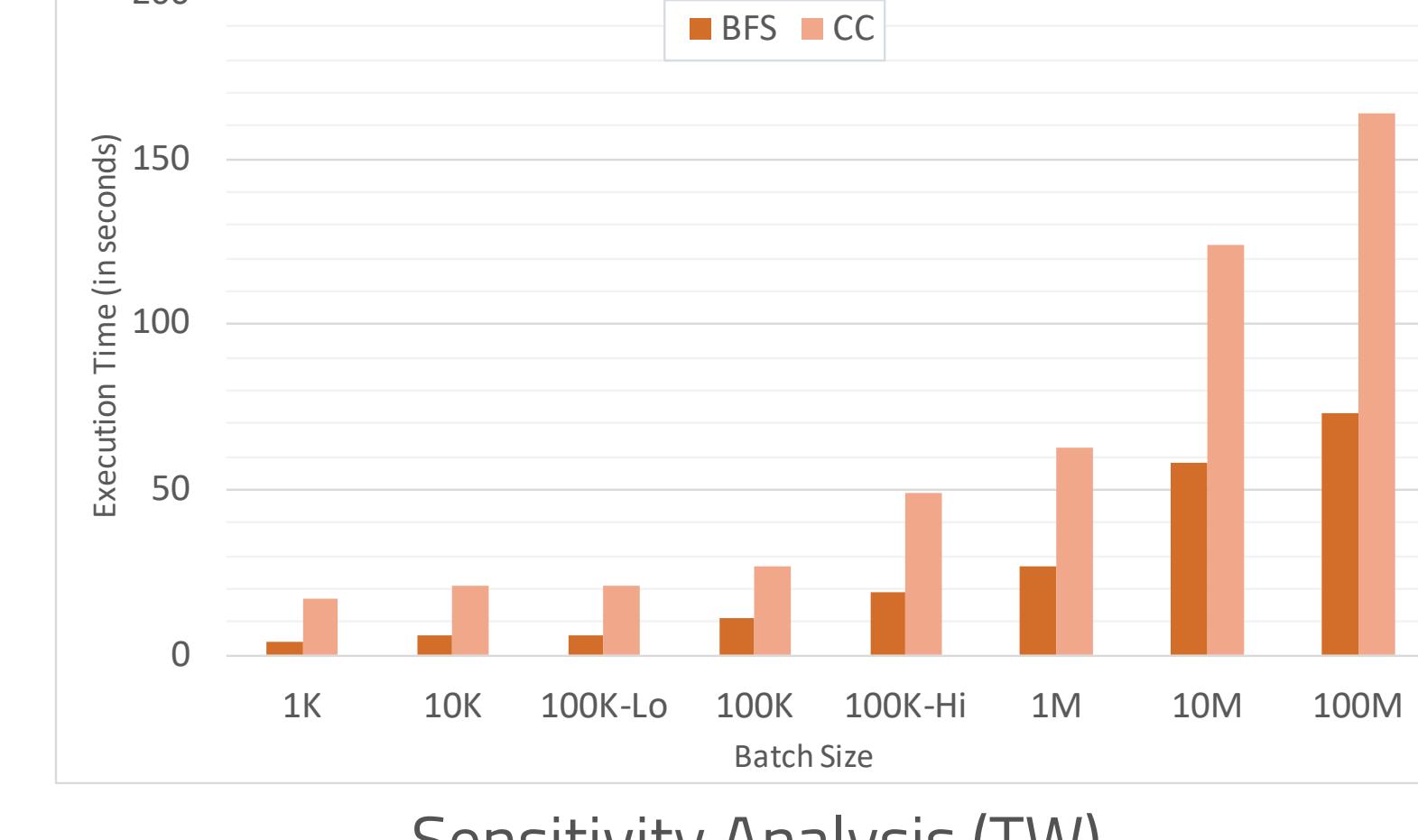


### Twitter (Insert:Delete 50:50)



Execution time (in seconds) for Recompute, TAG, Kickster-Lite, Wave for 100K mutations  
Wave is 6-23x faster than recomputation, 4-14x faster than TAG, and 2-6x faster than KS-Lite

### Execution Time (in seconds) vs Batch Size (TW)



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